## XP series

Mid-size flexible proportional joystick • non-contacting Hall effect technology

## DISTINCTIVE FEATURES

One or two axis
Dual and dual inverse analogue and PWM outputs
CAN J1939 \& CANopen
All metal mechanism construction

## ENVIRONMENTAL SPECIFICATIONS

- Operating Temperature: $-30^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}\left(-22^{\circ} \mathrm{F}\right.$ to $\left.158{ }^{\circ} \mathrm{F}\right)$
- Storage Temperature: $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}\left(-40^{\circ} \mathrm{F}\right.$ to $\left.185^{\circ} \mathrm{F}\right)$
- Sealing: IP66 (above panel subject to handle and final specification)
- EMC Immunity Level: EN61000-4-3 (exceeds)
- EMC Emissions Level: EN61000-6-3:2001, CPSPR 32:2015, Class B $30 \mathrm{MHz}-1 \mathrm{GHz}$
-ESD: EN61000-4-2 (exceeds)


## ELECTRICAL SPECIFICATIONS

- Analog output Voltage Range: $\pm 10 \% \times \mathrm{V}$ to $\pm 50 \% \times \mathrm{V}$
- Output at Center: V/2 $\pm(5 \% \times$ gain $)$
- Power Supply: $5 \mathrm{~V} \pm 0.5 \mathrm{~V}$ transient free; $3.3 \mathrm{~V} \pm 0.1 \mathrm{~V}$
- Output impedance: $10 \Omega$
- Overvoltage max: +20 V


## MECHANICAL SPECIFICATIONS

- Break out force: 3-5 N (subject to handle)
- Operating force: up to 12 N (subject to handle)
- Maximum force: Subject to handle
- Maximum Vertical Load: 1000 N (225 lbf) (subject to handle)
- Mechanical Angle of Movement: +/- $17.5^{\circ} \mathrm{X}$ \& Y axis (subject to limiter)
- Expected Mechanical Life: 10 million cycles
- Mass/weight: 500 g (17.64 oz) nominal

The company reserves the right to change specifications without notice.

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## (5) BUILD YOUR PART NUMBER



*Part number continues on next pages
**For configuration options 05, 06, and $0740 \%$ gain is the default
****Not available with left or right side features

## HANDLE OPTIONS



| HANDLE | AQ | AR |
| :--- | :---: | :---: |
| MATERIAL | Aluminium | Aluminium |
| FINISH | Anodized | Anodized |
| STANDARD COLOR | Black | Black |
| NOTES |  | Uses APEM IA switch |
| SEALING | IP66 | IP66 |
| MAX HORIZONTAL LOAD | TBC | TBC |
| MAX Z LOAD | $3 N m$ | $3 N m$ |



| HANDLE | UR | MF |
| :--- | :---: | :---: |
| MATERIAL | Reinforced nylon | Reinforced nylon |
| FINISH | Anodized | Texture |
| STANDARD COLOR | Black | Black |
| SEALING | IP66 | IP66 |
| MAX HORIZONTAL LOAD | TBC | TBC |
| MAX Z LOAD | 5 Nm | 5 Nm |

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## BUILD YOUR PART NUMBER (continued)




X
None


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R
Right side features for left hand


L Left side features for right hand


## SIDE CONFIGURATION



S001 HR series


S003 $1 \times \mathrm{IX}$ series


$\square$



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Custom options available please contact APEM for further details.


## (5) BUILD YOUR PART NUMBER (continued)



Inquire for custom options

NOTES:

* Standard option is a black FNR series, no marking. Many other options available (see APEM FNR datasheet)
** Standard option is a black HR series, single tab, $40 \%$ gain, single output. Many other options available (see APEM HR datasheet)
*** Only available without faceplate trim, not compatible with R003 or R004


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FXXX No switches


F003 $3 \times 1 \mathrm{X}$ series


F006
$6 \times I X$ series


F009
$1 \times$ HR series horizontal


F001
$1 \times \mathrm{IX}$ series


F004
$4 \times I X$ series


F007


F010
xHR series vertical



## REAR PLATE



RXXX None
R001 $1 \times$ IX series
R002 $2 \times$ IX series


R003 $1 \times$ FNR series ON-OFF-ON

R004
$1 \times$ FNR series MOM-OFF-MOM


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TERMINATION - STANDARD CENTRAL


TERMINATION - STANDARD RIGHT ANGLE


## (1) MOUNTING

When mounting the joystick, consideration should be given to the position so that unnecessary risk of damage is minimised. If the joystick is intended for use in a mobile enclosure then care must be taken to protect the joystick from damage caused by dropping. Basic precautions such as mounting it at the lightest end of the enclosure so it doesn't hit the ground first or by protecting it with a guard should always be implemented for long term reliability.

DROP-IN MOUNT CUT-OUT AND INSTALLATION BEZEL OPTION 6


- The joystick is dropped into the panel cut-out.
- Supplied with M5 low profile cap head bolts, spring washers and nuts. Must be torqued to 0.7 Nm
- When mounted this way the gaiter forms part of the panel seal however an addition seal is provided to ensure good bezel to panel contact.

UNDER PANEL MOUNT CUT-OUT AND INSTALLATION BEZEL OPTION 0

-When mounted this way the panel acts as the bezel and no separate bezel is needed.

- Supplied with sealed M5 screws spring washers and nuts. Must be torqued to 0.7 Nm
- When mounted this the upper part of the gaiter forms part of the panel seal, however an addition seal is provided to ensure good bezel to panel contact.

NOTES:

1. Dimensions are in $\mathrm{mm} /$ (inch).
2. The dimensions shown are for XP AR handle. For specific dimensions of this or any other configuration please refer to APEM.
3. When sub panel mounting, great care should be taken not to damage the boot, or any of the mechanism under the boot.
All panel cut-outs should be free from sharp edges and debris that may damage the boot.

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## $\lambda$ <br> CONNECTIONS

The analogue and PWM joysticks are fitted as standard with $180 \mathrm{~mm}(+/-20 \mathrm{~mm})$ harnesses. Terminated to a 26 way housing TE 1-1827863-3.
Non standard connectors can be fitted upon request.

| EXAMPLE WIRING TABLE |  |  |
| :---: | :--- | :--- |
| TE CONNECTIVITY 1-1827863-3 PINOUT |  |  |
| PIN | COLOUR | FUNCTION |
| A1 | RED | +VA |
| B1 | BLACK | OVA |
| A2 | RED | +VB |
| B2 | BLACK | OVB |
| A3 | BLUE | X Axis A |
| B3 | YELLOW | Y Axis A |
| A4 | BROWN | X Axis B |
| B4 | WHITE | Y Axis B |
| A5 | GREEN | Z Axis A |
| B5 | ORANGE | Z Axis B |
| A6 | GREEN | Centre Tap |
| B6 | ORANGE | Centre Detect |
| A7 | ORANGE | Switch Common |
| B7 | BLUE | Front Switch |
| A8 | RED | Enable Switch Common |
| B8 | RED | Enable Switch Normally Open |
| A9 | RED | Enable Switch Normally Closed |
| B9 | GREEN | Handle Function 1 |
| A10 | BLUE | Handle Function 2 |
| B10 | ORANGE | Handle Function 3 |
| A11 | GREEN | Handle Function 4 |
| B11 | BLUE | Handle Function 5 |
| A12 |  |  |
| B12 |  |  |
| A13 |  |  |
| B13 |  |  |
|  |  |  |

CONNECTOR DETAIL
26 way housing TE 1-1827863-3


## MATERIALS

- Shaft: Stainless steel
- Boot: Neoprene
- Body: Zinc
- Handles:

AR \& AQ - Anodised aluminium
UR: Reinforced Nylon
MF: Reinforced Nylon

## $\rightarrow$ <br> TERMINATION (CAN OUTPUTS ONLY)

- The XP series CAN options are supplied with 200mm harness terminated with an industrial connector.
- Connector detail: DTM04-6P


| PIN | Connection | Colour |
| :---: | :---: | :---: |
| 1 | CAN LO | White |
| 2 | CAN HI | Green |
| 3 | ID LSB | Blue |
| 4 | ID MSB | Yellow |
| 5 | $0 V$ | Black |
| 6 | +12 V | Red |

## CAN J1939 INTERFACE

 SPECIFICATIONThe XP Series CAN options data is delivered on a CAN 2.0B compliant physical interface. Two additional signals allow configuration of the controller Source Address. Controller messages are delivered per the SAE J1939-71 message protocol.

CAN 2.0B INTERFACE PARAMETERS

- Baud rate: 250 kbps
- Transmission repetition rate: 50 ms
- BJMI/EJMI interval time: 20ms
- Terminating resistor: No


## CANopen INTERFACE SPECIFICATION

- Baud rate: 250 kbps
- Node ID: 20h
- Buttons: 1AOH (180H + NODE ID)
- Analog (axis) outputs: 2AOh (280h + Node ID)
- Heartbeat ( 500 ms ): 720h (700h + Node ID)
- Axis resolution: 8 bit
- Network Management: Auto start enabled


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## (4) voltage output options

SINGLE OUTPUT - CONFIGURATION 1


DUAL OUTPUT - CONFIGURATION 3


DUAL OUTPUT - CONFIGURATION 4





$$
\begin{array}{ll}
\hline-{ }^{-------} & \text {Output 1 } \\
\text { Output } 2
\end{array}
$$

## CONFIGURATION

## POWER SUPPLY

The analogue XP series is designed to be powered by a regulated $5 \mathrm{~V} \pm 0.5 \mathrm{~V}$ power supply. The outputs are ratiometric, making a stable, noise free, power supply essential.

## MAGNETIC IMMUNITY AND SYSTEM DESIGN

The XP series incorporates internal magnetic screening to minimise the effect of external magnetic fields. Mounting or operating the joystick close to strong magnetic fields is not recommended. System designers should follow best practice when incorporating the XP series joystick into their products.
Care should be taken to decouple the power supply properly and to employ adequate EMC shielding.

## CENTER DETECT (CD)

Where selected, (configuration 1 types) the output on this additional cable will be 0 V while the joystick is inactive. Should either the $X$ or $Y$ outputs change outside of the centre tolerance, indicating that the joystick has been operated, the centre detect signal will switch to 5 V .
Within the joystick this output is pulled high by a 2 K 2 resistor and is decoupled by a 100 nF capacitor to 0 V .
This output is designed for use in applications requiring an enable/disable signal that is separate from the main $\mathrm{X}, \mathrm{Y}$ outputs. It is not recommended for use as a safety feature or a method of "person-present" detection.

## CENTER TAP REFERENCE (CT)

Where selected, (configurations 1, 3 and 4) the joystick also outputs a centre reference voltage that is set at $50 \%$ ( $\pm 1 \%$ ) of the supply voltage.
This output can be used to check the integrity of the power supply applied to the joystick. A reading on this output, outside of the specified tolerance suggests a problem with the power supply to the joystick.
The other purpose of this output is to act as a reference equal to the voltage output when the lever is at centre.
Measuring the voltage outputs relative to CT rather than 0 V eliminates inaccuracies created by variation in supply voltage.

## GAIN OPTIONS

The voltage output on the HE outputs, at full scale deflection is determined by the gain. The gain is expressed as a percentage of the voltage supplied. Therefore (assuming a 5 V supply) a joystick specified with $\pm 25 \%$ gain would yield 1.25 V at South, 2.5 V at centre and 3.75 V at North.

A range of gain options are available as standard for configurations 01,03 and 04 . For output options 05 , 06 and $07,40 \%$ gain is the default specification. All joysticks are supplied pre-set and no further calibration is needed throughout the lifetime of operation.

## OUTPUT IMPEDANCE

The voltage outputs at centre and at each end of travel are specified across an infinite load, with no current flowing.
The output impedance specified in the electrical specification should be taken into account when designing a system. Load resistance of less than 10 K Ohms is not recommended.

## MECHANISM

The omni-directional mechanism utilises an extremely robust ball-socket pivot. This construction yields an end product that is extremely resistant to vertical impact.
Furthermore, it constantly withstands high pull, push, rotational or horizontal forces that the product may be subject to, during life.

## SPRINGING

All XP series are offered sprung to centre. The standard spring force requires $3-5 \mathrm{~N}$ to off-centre the joystick.

## GUIDED FEEL

The XP series is supplied as standard with guided feel. A joystick with guided feel moves more readily towards the poles ( $\mathrm{N}, \mathrm{S}, \mathrm{E}$ and W ) and whilst it can still move away from the poles, the force required to do so is greater. For non-guided feel please contract APEM for availability.

## EXTERIOR COMPONENTS

APEM has a huge range of control components, and only some basic options have been included in the standard XP configuration. Many other options are available as a custom XP configuration, refer to individual component datasheets for details.

